## Quattro 650H/HS

## Four-axis parallel robot achieves high speed and high precision

- Ethernet capability to control the robot through the familiar programming language (IEC 61131-3) of Machine Automation Controller NJ/NX Series
- Four-axis arm evenly distributes the load on the robot
- Fast and high-precision conveyance and assembly
- Designed with a high payload to support multi-hand (multi-picking)
- · Supports fast Pick & Place on a fast conveyor
- Meets the sanitary standards of the United States Department of Agriculture for prevention of product contamination
- Maximum working diameter 1,300 mm
- Working height 500 mm
- Maximum payload 15 kg
- Weight 117 kg
- Protection IP66 (HS type)



## **Specifications**

Product name		Quattro		
	Size	650		
	Туре	Н	HS	
Model		1721□-2600□	1721□-2601□	
Number of axes		4	4	
Mounting		inverted		
Working volume	X,Y axis (stroke)	1300 mm		
	Z axis (stroke)	500 mm		
		0° (fixed) (P30)		
	theta axis (rotation angle)	±46.25° (P31)		
		±92.5° (P32)		
		±185° (P34)		
Maximum Payload		6 kg (P30: 15kg)		
Repeatability		±0.10mm		
	Payload 0.1 kg	0.30s *1, 0.46 s *2		
	Payload 1.0 kg	0.36s <b>*</b> 1, 0.47 s <b>*</b> 2		
Cycle times, sustained (at 20°C ambient)	Payload 2.0 kg	0.37s <b>*</b> 1, 0.52 s <b>*</b> 2		
(at 20 0 ambiont)	Payload 4.0 kg	0.41s *1, 0.58 s *2		
	Payload 6.0 kg	0.43s <b>*</b> 1, 0.61 s <b>*</b> 2		
Power Requirements		24 VDC: 11 A (eAIB, SmartController) 200 to 240 VAC: 10 A, single-phase		
Protection	Base	IP65 (with optional cable sealing kit)	IP66	
	Tooling	IP67	IP67	
Environment	Ambient Temperature	1 to 40°C		
Requirements	Humidity Range	5 to 90% (non-condensing)		
Weight		117 kg		
USDA-Accepted for meat and poultry processing			Yes	
Basic configuration	Controller	SmartController EX		
	On-board I/O (Input/Output)	12/8		
	Conveyor tracking input	4		
	RS-232C serial communications port	1		
	Programming environment	ACE, PackXpert, PLC		
	ACE Sight	Yes		
	ePLC Connect	Yes		
	ePLC I/O	Yes		
Connectable controller	*3	SmartController EX, NJ/I	NX Series *4	

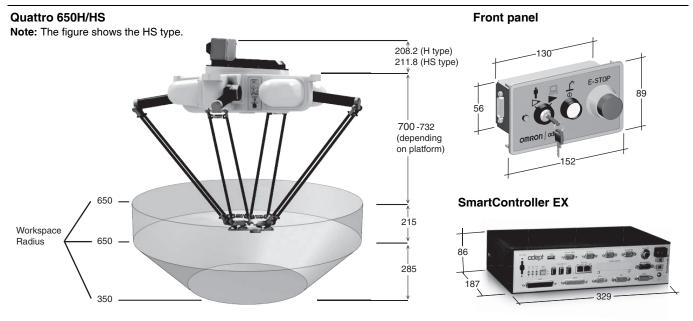
<sup>\*1.</sup> Adept cycle, in mm (25/305/25)

<sup>\*2.</sup> Extended cycle, in mm (25/700/25)

**<sup>\*3.</sup>** Choose a controller to suit your application.

**<sup>\*4.</sup>** The robot version 2.3.C is required to connect with the NX/NJ Series.

Dimensions (Unit: mm)



Four choices of platform offer different ranges of rotation.

Appearance				
Туре	P30	P31	P32	P34
Rotation angle	No rotation	±46.25°	± 92.5°	±185°
Maximum Payload	H: 15 kg, HS: 12 kg	H: 6 kg, HS: 3 kg	H: 6 kg, HS: 3 kg	H: 6 kg, HS: 3 kg

**Note:** The platform appearances of the H type are shown above. The platform of the HS type is made of stainless steel.

## **Robot Parts Code and Bundled Accessories**

Туре	Quattro with EX Controller	Quattro Add-On	
Quattro 650H P30	17214-26000	17213-26000	
Quattro 650H P31	17214-26001	17213-26001	
Quattro 650H P32	17214-26002	17213-26002	
Quattro 650H P34	17214-26004	17213-26004	
Quattro 650HS P30	17214-26010	17213-26010	
Quattro 650HS P31	17214-26011	17213-26011	
Quattro 650HS P32	17214-26012	17213-26012	
Quattro 650HS P34	17214-26014	17213-26014	
Overview	Robot + eAIB+ SmartController EX + required connection cables	Robot + eAlB + required connection cables	
Purpose	Typical for use in single robot system and multi-robot systems.	Typically added to systems with an existing SmartController EX to create multi-robot systems	
Bundled Accessories	<ul> <li>XSYS cable with jumpers, 2m/6ft (13323-000)</li> <li>SmartController EX (09200-000)</li> <li>XSYS cable, 5m/15 ft (11585-000)</li> <li>1394 latch cable, 5m/15 ft, 13632-045)</li> <li>Front panel kit (90356-10358)</li> <li>eV+ license to connect to controller (14529-103)</li> </ul>	<ul> <li>XSYS cable with jumpers, 2m/6ft (13323-000)</li> <li>XSYS cable, 5m/15 ft (11585-000)</li> <li>DB9 splitter (00411-000)</li> <li>1394 latch cable, 5m/15 ft, 13632-045)</li> <li>eV+ license to connect to controller (14529-103)</li> </ul>	

Note: OMRON also provides other types of model. Ask your OMRON sales representative for details.